**GLS-2200** 



High Speed (90% reflectivity)  Low Power (90% reflectivity)  Low Power (90% reflectivity)  - 350m  Close Scan (9% reflectivity)  - 350m  Close Scan (9% reflectivity)  - 350m  Close Scan (9% reflectivity)  40m   Canning Module  Scan mode <sup>27</sup> Detail High Speed Low Power Scan data rate (Maximum points per second)  Laser Class  Laser  Scan ing Module  Scan ing Mo	100m   210m   210m   500m   40m   Standard   60,000   Class 3R     3.1mm (\overline{\sigma})   At 1 to 150m   At 1 to 150m					
Detail	100m 210m 210m 500m 40m  Standard 60,000 Class 3R					
Detail   (90% reflectivity)   100m   100m   100m   100m   11gh Speed (90% reflectivity)   130m   210m   100m   100m   210m   100m	210m 210m 500m 40m  Standard 60,000 Class 3R					
High Speed (90% reflectivity)	210m 210m 500m 40m  Standard 60,000 Class 3R					
Low Power (90% reflectivity)         130m         210m           Standard (90% reflectivity)         -         350m           Close Scan (9% reflectivity)         40m         40m           Scanning Module         -         350m           Scan mode <sup>72</sup> Detail         High Speed         Low Power           Scan data rate (Maximum points per second)         120,000         120,000         48,000           Laser         Class 3R         Class 1           Scanning Density (Resolving Power)         √54mm         √51mm           Spot Size(FWHM)         1 to 20m         1 to 150m           Point Increment         Minimum 3.1mm (At 10m)           Maximum Point Number         V:15,202 Pt/Line (270°) H:20,268 Pt/Line (360°)           Field of View         V:270° H:360°           Angle Accuracy         3.1mm (σ)         3.1 mm (σ)         3.7mm (σ)           At 1 to 90m         At 1 to 110m         At 1 to 110m         At 1 to 110m           Surface Accuracy         At 1 to 90m         At 1 to 110m         At 1 to 110m           Measuring Range         0.3 to 2.0m         0.3 to 2.0m           Measuring Range         0.3 to 2.0m         0.3 to 2.0m           Measuring Range         Tele: 8.9°(V) x 11.9°(H)	210m 500m 40m  Standard 60,000 Class 3R					
Low Power (90% reflectivity)         130m         210m           Standard (90% reflectivity)         -         350m           Close Scan (9% reflectivity)         40m         40m           Scanning Module           Scan mode <sup>72</sup> Detail         High Speed         Low Power           Scan data rate (Maximum points per second)         120,000         120,000         48,000           Laser         Class 3R         Class 1           Scanning Density (Resolving Power)         \$\sum_{\text{Scanning Density}}\$         \$\sum_{\text{11mm}}\$           Spot Size(FWHM)         \$\sum_{\text{11mm}}\$         \$\sum_{\text{11mm}}\$           Point Increment         Minimum 3.1mm (At 10m)           Maximum Point Number         \$\sum_{\text{15,202}}\$ Pt/Line (270°) H:20,268 Pt/Line (360°)           Field of View         \$\sum_{\text{2.707}}\$ H:360°           Angle Accuracy         \$\text{3.1mm}(\sigma)\$         3.1 mm (\sigma)\$         3.7 mm (\sigma)           Distance Accuracy         \$\text{3.1mm}(\sigma)\$         3.1 mm (\sigma)\$         3.7 mm (\sigma)\$           Surface Accuracy         \$\text{4.1 to 90m}\$         \$\text{4.1 to 110m}\$         \$\text{4.1 to 110m}\$           Height Measurement         \$\text{Measuring Range}\$         \$\text{0.3 to 2.0m}\$           Measuring Range </td <td>500m 40m Standard 60,000 Class 3R 3.1mm (σ)</td>	500m 40m Standard 60,000 Class 3R 3.1mm (σ)					
Standard   Gook reflectivity   Gook Scan (9% reflectivity   Gook Scan (19% reflectivity   Gook Sc	500m 40m Standard 60,000 Class 3R 3.1mm (σ)					
Close Scan (9% reflectivity)   40m	40m  Standard 60,000 Class 3R  3.1mm (σ)					
Scan mode*²         Detail         High Speed         Low Power           Scan data rate (Maximum points per second)         120,000         48,000           Laser Class         Class 3R         Class 1           Laser Class         1064nm           Scanning Density (Resolving Power)	60,000 Class 3R 3.1mm (σ)					
Scan mode*²         Detail         High Speed         Low Power           Scan data rate (Maximum points per second)         120,000         48,000           Laser Class         Class 3R         Class 1           Laser         1064nm           Scanning Density (Resolving Power)	60,000 Class 3R 3.1mm (σ)					
Scan data rate (Maximum points per second)         120,000         120,000         48,000           Laser Class         Class 3R         Class 1           Scanning Density (Resolving Power)         054mm         054mm         054mm           Spot Size(FWHM)         1 to 20m         1 to 150m         1 to 150m           Point Increment         Minimum 3.1mm (At 10m)         1 to 150m         1 to 150m           Maximum Point Number         V:15,202 Pt/Line (270°) H:20,268 Pt/Line (360°)         Field of View         V:270°/ H:360°           Angle Accuracy         3.1mm (σ)         3.1 mm (σ)         3.7mm (σ)           Distance Accuracy         3.1mm (σ)         3.1 mm (σ)         3.7mm (σ)           Surface Accuracy         At 1 to 90m         At 1 to 110m         At 1 to 110m           Height Measurement         Measuring Range         0.3 to 2.0m         0.3 to 2.0m           Measuring Range         0.3 to 2.0m	Class 3R 3.1mm (σ)					
Laser         1064nm           Scanning Density (Resolving Power)         φ ≤4mm         φ ≤11mm           Spot Size(FWHM)         1 to 20m         1 to 150m           Point Increment         Minimum 3.1mm (At 10m)           Maximum Point Number         V:15,202 Pt/Line (270°) H:20,268 Pt/Line (360°)           Field of View         V:270°/ H:360°           Angle Accuracy         H: 6" / V: 6"           Joistance Accuracy         3.1 mm (σ)         3.7 mm (σ)           At 1 to 90m         At 1 to 110m         At 1 to 110m           Height Measurement         At 1 to 90m         At 1 to 110m         At 1 to 110m           Measuring Range         0.3 to 2.0m           Measuring Range         0.3 to 2.0m         Measuring Accuracy           Camera         Wide: Diagonal 170°           Field Angle         Tele.: 8.9°(V) x 11.9°(H)           Number of pixels         Both Wide & Tele. Smegapixels           HDR         Yes           Filt Sensor         Liquid 2-axis tilt-sensor           Compensation Range         ±6'           Obsplay Unit         TFT-LCD 3.5 VGA with touch-panel	3.1mm (σ)					
Scanning Density (Resolving Power)   Ø ≤ 4mm						
Spot Size(FWHM)         Φ ≦4mm         Φ ≦11mm           Point Increment         Minimum 3.1mm (At 10m)           Maximum Point Number         V:15,202 Pt/Line (270°) H:20,268 Pt/Line (360°)           Field of View         V:270°/ H:360°           Angle Accuracy         H: 6″ / V: 6″           Distance Accuracy         3.1mm (σ)         3.7mm (σ)           At 1 to 90m         At 1 to 110m         At 1 to 110m           Surface Accuracy         At 1 to 90m         At 1 to 110m         At 1 to 110m           Height Measurement         Measuring Range         0.3 to 2.0m         At 1 to 110m         At 1 to 110m           Measuring Accuracy         3.0mm (Req. Special Target)         Camera           Field Angle         Wide : Diagonal 170°         Tele: :8.9°(V) x 11.9°(H)           Number of pixels         Both Wide & Tele. 5megapixels           HDR         Yes           Filt Sensor         Liquid 2-axis tilt-sensor           Type         Liquid 2-axis tilt-sensor           Compensation Range         ±6′           Display Unit         Type         TFT-LCD 3.5 VGA with touch-panel						
To 20m						
To 20m						
Maximum Point Number         V:15,202 Pt/Line (270°) H:20,268 Pt/Line (360°)           Field of View         V:270°/ H:360°           Angle Accuracy         H: 6" / V: 6"           Distance Accuracy         3.1mm (σ)         3.7mm (σ)           At 1 to 90m         At 1 to 110m         At 1 to 110m           Surface Accuracy         At 1 to 90m         At 1 to 110m         At 1 to 110m           Heasuring Range         0.3 to 2.0m         Measuring Accuracy         3.0mm (Req. Special Target)           Camera         Wide : Diagonal 170°         Tele.: 8.9°(V) x 11.9°(H)           Number of pixels         Both Wide & Tele. 5 megapixels           HDR         Yes           Tilt Sensor         Type         Liquid 2-axis tilt-sensor           Compensation Range         ±6'           Display Unit         Type         TFT-LCD 3.5 VGA with touch-panel						
Field of View         V:270°/ H:360°           Angle Accuracy         H: 6" / V: 6"           Distance Accuracy         3.1mm (σ)         3.7mm (σ)           Surface Accuracy         At 1 to 90m         At 1 to 110m         At 1 to 110m           Surface Accuracy         At 1 to 90m         At 1 to 110m         At 1 to 110m           Height Measurement         Heasuring Range         0.3 to 2.0m           Measuring Accuracy         3.0mm (Req. Special Target)           Camera         Vide : Diagonal 170°           Field Angle         Tele.: 8.9°(V) x 11.9°(H)           Number of pixels         Both Wide & Tele. 5 megapixels           HDR         Yes           Tilt Sensor         Type           Compensation Range         ±6'           Display Unit         Type           Type         TFT-LCD 3.5 VGA with touch-panel						
Field of View         V:270°/ H:360°           Angle Accuracy         H: 6" / V: 6"           Distance Accuracy         3.1mm (σ)         3.7mm (σ)           Surface Accuracy         At 1 to 90m         At 1 to 110m         At 1 to 110m           Surface Accuracy         At 1 to 90m         At 1 to 110m         At 1 to 110m           Height Measurement         Heasuring Range         0.3 to 2.0m           Measuring Accuracy         3.0mm (Req. Special Target)           Camera         Vide : Diagonal 170°           Field Angle         Tele.: 8.9°(V) x 11.9°(H)           Number of pixels         Both Wide & Tele. 5megapixels           HDR         Yes           Tilt Sensor         Type           Compensation Range         ±6'           Display Unit         Type           Type         TFT-LCD 3.5 VGA with touch-panel						
3.1mm (σ)         3.1 mm (σ)         3.7 mm (σ)           At 1 to 90m         At 1 to 110m         At 1 to 110m           Surface Accuracy         1.0 mm (σ) <sup>-5</sup> At 1 to 90m         At 1 to 110m         At 1 to 110m           Height Measurement           Measuring Range         0.3 to 2.0 m           Measuring Accuracy         3.0 mm (Req. Special Target)           Camera           Field Angle         Wide : Diagonal 170°           Tele. : 8.9°(V) x 11.9°(H)           Number of pixels         Both Wide & Tele. 5 megapixels           HDR         Yes           Titl Sensor         Liquid 2-axis tilt-sensor           Compensation Range         ±6'           Display Unit         Type         TFT-LCD 3.5 VGA with touch-panel           Others						
Distance Accuracy         3.1 mm (σ)         3.1 mm (σ)         3.7 mm (σ)           Surface Accuracy         1.0 mm (σ) <sup>-5</sup> At 1 to 90m         At 1 to 110m         At 1 to 110m           Height Measurement           Measuring Range         0.3 to 2.0 m           Measuring Accuracy         3.0 mm (Req. Special Target)           Camera           Field Angle         Wide : Diagonal 170°           Tele. : 8.9°(V) x 11.9°(H)           Number of pixels         Both Wide & Tele. 5 megapixels           HDR         Yes           Titl Sensor         Liquid 2-axis tilt-sensor           Compensation Range         ±6'           Display Unit           Type         TFT-LCD 3.5 VGA with touch-panel           Others						
At 1 to 90m	At 1 to 150m					
At 1 to 90m	710 130111					
Height Measurement         0.3 to 2.0m           Measuring Range         0.3 to 2.0m           Measuring Accuracy         3.0mm (Req. Special Target)           Earnera         Wide : Diagonal 170°           Field Angle         Tele.: 8.9°(V) x 11.9°(H)           Number of pixels         Both Wide & Tele. 5megapixels           HDR         Yes           Tilt Sensor         Liquid 2-axis tilt-sensor           Compensation Range         ±6′           Display Unit         TFT-LCD 3.5 VGA with touch-panel           Others         TFT-LCD 3.5 VGA with touch-panel	At 1 to 150m					
Measuring Range         0.3 to 2.0m           Measuring Accuracy         3.0mm (Req. Special Target)           Camera           Field Angle         Wide : Diagonal 170°           Tele. : 8.9°(V) x 11.9°(H)         Number of pixels           HDR         Both Wide & Tele. 5megapixels           HDR         Yes           Tilt Sensor         Liquid 2-axis tilt-sensor           Compensation Range         ±6'           Display Unit         TFT-LCD 3.5 VGA with touch-panel           Others         TFT-LCD 3.5 VGA with touch-panel	, , , , , , , , , , , , , , , , , , , ,					
Measuring Accuracy Camera  Field Angle Field Angle Field Poly and Service Serv						
Camera           Field Angle         Wide : Diagonal 170°           Tele. : 8.9°(V) x 11.9°(H)           Number of pixels         Both Wide & Tele. 5megapixels           HDR         Yes           Titl Sensor         Liquid 2-axis tilt-sensor           Type         Liquid 2-axis tilt-sensor           Compensation Range         ±6'           Display Unit         TFT-LCD 3.5 VGA with touch-panel           Others         Others						
Field Angle  Tele.: 8.9°(V) x 11.9°(H)  Number of pixels Both Wide & Tele. 5megapixels HDR Yes  Tilt Sensor  Type Liquid 2-axis tilt-sensor  Compensation Range ±6′  Display Unit  Type TFT-LCD 3.5 VGA with touch-panel						
Tele.: 8.9°(V) x 11.9°(H)     Number of pixels						
Number of pixels HDR Yes  Filt Sensor  Type Liquid 2-axis tilt-sensor  Compensation Range  Display Unit  Type TFT-LCD 3.5 VGA with touch-panel Others	•					
HDR Yes  Filt Sensor  Type Liquid 2-axis tilt-sensor  Compensation Range ±6'  Display Unit  Type TFT-LCD 3.5 VGA with touch-panel Others						
Tilt Sensor Type Liquid 2-axis tilt-sensor Compensation Range ±6' Display Unit Type TFT-LCD 3.5 VGA with touch-panel Others						
Type Liquid 2-axis tilt-sensor Compensation Range ±6'  Display Unit Type TFT-LCD 3.5 VGA with touch-panel Others						
Compensation Range ±6′ Display Unit Type TFT-LCD 3.5 VGA with touch-panel Others						
Display Unit Type TFT-LCD 3.5 VGA with touch-panel Others						
Type TFT-LCD 3.5 VGA with touch-panel Others						
Others						
	Spot Size Ø1mm (1m) / Ø4mm (1.5m)					
	Magnification range 1m					
Interface Interface						
Card Slot SD card (SDHC Class 6 or more)	SD card (SDHC Class 6 or more)					
Power Supply						
Internal Battery BDC72						
Capacity 5240mAh / 1pce × 4pcs	5240mAh / 1pce × 4pcs					
Nominal Voltage 7.4V / 1pce x pcs	7.4V / 1pce x pcs					
Working Duration 2.5 hours (4pcs continuous scanning)						
Appearance						
Dimension 228(D)×293 (W)×390 (H) mm(With handle & Base)	228(D)×293 (W)×390 (H) mm(With handle & Race)					
Inst height 226mm (From top of base to center of Miller)						
Weight 10kg (Include Base and Battery)						
Condition						
-5 TO ±45°C						
Operating Temperature -5 to +45°C Storage Temperature -20 to +60°C						



### **Standard Components**

\*1: It will be different depending on the condition. \*2: Specification of Close Scan mode is listed inside the catalog. \*3: When the smoothing function is used for MAGNET Collage Ver2.3 or later.

- GLS-2200
- Battery (BDC72) 4 pieces
- Battery Charger (CDC77) 2 pieces
- Charging Cable (EDC113) 2 pieces
- Carrying case
- Silica gel
- Cloth wipe • SD card
- SD card case
  - Tool kit
  - Target sheet
  - Centering target
  - Instruction manual
  - Warranty card



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#### <Contact to>

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# GLS-2200 Series CAPTURE



**3D Laser Scanner** 

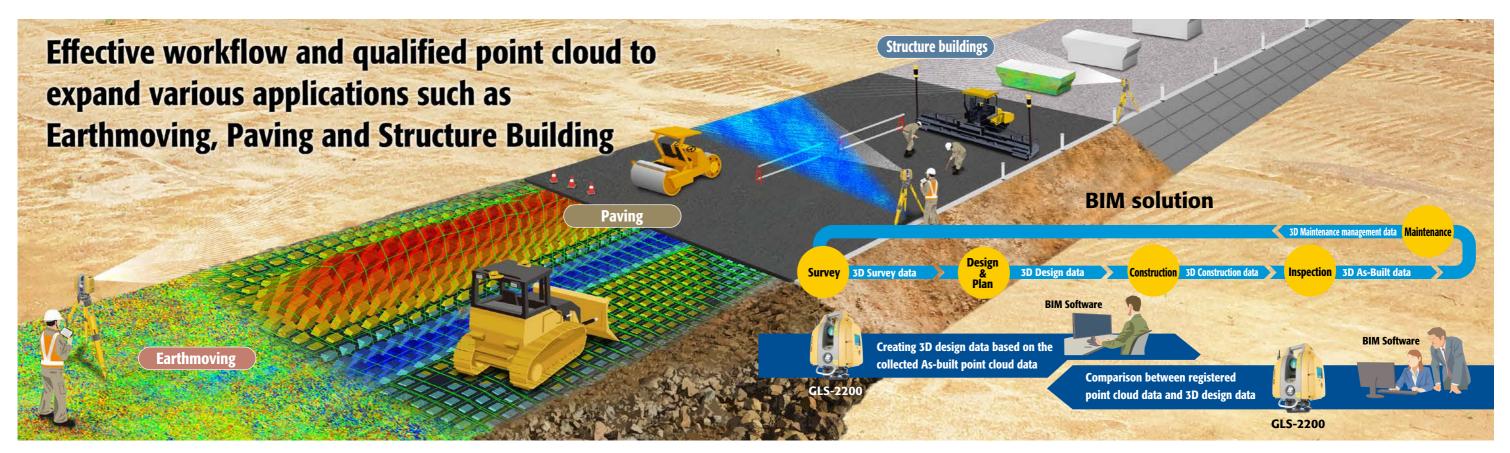




### **Best fit for ICT construction,** expanding various applications

Precise 3D point cloud data maintains accuracy

- Resection, occupation/backsight on-board program
- 360° prism, long-range target scan
- Surface accuracy 1mm ( $\sigma$ )
- HDR image capture creates clear point cloud data
- Remote control
- Japanese quality



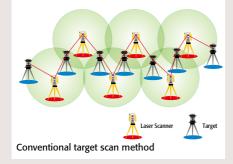
### Effective workflow with verified point cloud data

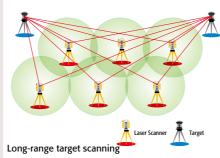
### Long-range target scan

200m range for the resection or traverse methods greatly reduces the need to change the target positions, even on large sites.

#### 360°prism compliant

Scan targets from anywhere without changing the direction of the target scan.





### 500m Middle 350m Short 130m

## Three modules are available for measuring different ranges

The product measures distances ranging from short, interior measurement of a facility to asbuilt civil engineering projects and other large structures.



## Occ/Backsight, and Resection program on board

Survey method registration can be done at the site with the program on board, so you can save the working time at the software side.



## Supports eight measurement modes

GLS-2200 provides a wide range of measuring modes to accommodate different job site demands to achieve accurate measurement and increase productivity regardless of site conditions.



#### Road mode

The road mode can scan even dark-colored surfaces such as paved asphalt and ICT paving construction.

### Improved point cloud data quality

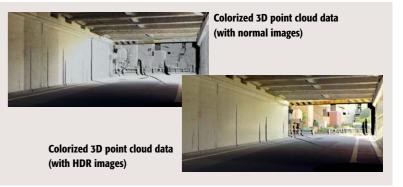
### Surface accuracy 1mm\*( $\sigma$ )

Road mode is a fit for ICT paving construction, as-builts and QA/QC for BIM.

\* Standard deviation (1 $\sigma$ ) 1mm. Processed with MAGNET Collage

### HDR image capture creates clear point cloud data

Normal images of 3D point cloud data tend to have washed-out whites and unrecognizable dark spaces. The colorized 3D point cloud data creates HDR images with more natural and realistic colors





## Easy and intuitive on-board control software

With the on-board control software, the scanning can be simply started with one-touch of button. Together with color graphical display, scanning operation can be intuitively proceeded.



## WLAN Connectivity for connecting to an Android Tablet \*

WLAN capability enables users to remotely control their Android tablets. All activity in the tablet is relayed to the scanner.

\* Offered as an option in some areas.



### **Dual cameras**

Dual coaxial 5MP cameras capture both high-speed 170° wide angle and 8.9° narrow images.



rrow angle camera



## **Dual-axis-tilt compensation secures** the right registration

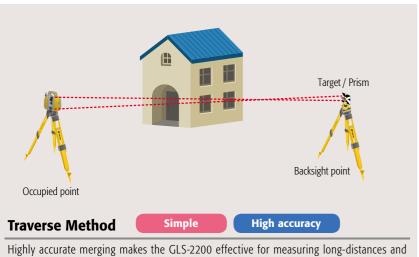
The dual-axis-tilt compensation (x/- 6') is identical to that available on total stations. The scan data can be accurately registered using the MAGNET Collage post-processing software.

### **Supporting Various Registration Methods**

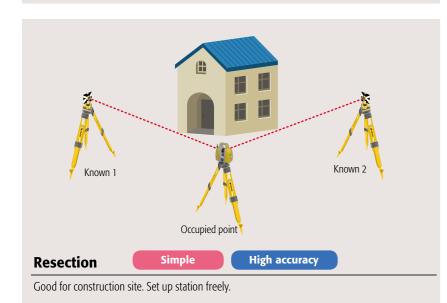
The GLS-2200 can execute field work similar to that of total stations by supporting various registration methods.

	Traverse	Resection	Tie Point	Shape Matching	Manual Registration	Station Set
Target Setting	Necessary (1 point)	Necessary (More than 2 points)	Necessary (many)	Unnecessary	Unnecessary	
Localization	Possible	Possible	Possible	Not Possible	Not Possible	Combined Registration
Working Time	Quick	Quick	Long *	Quick	Quick	
Registration Accuracy	High	High	Standard	Low	Low	

\* Multiple target scanning is necessary

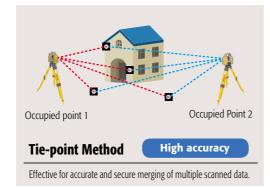


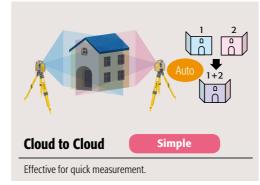
complex objects.

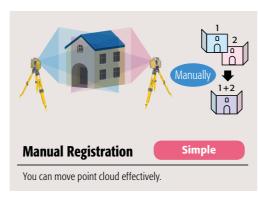


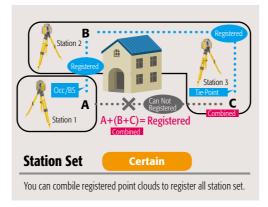
#### Maximum range at reflectivity

Reflectivity	9%	9% 18%	
Short	<b>40m</b> (Detail)	<b>90m</b> (High Speed / Low Power)	130m (High Speed / Low Power)
Middle	<b>40m</b> (Detail)	150m (Standard)	<b>350m</b> (Standard)
Long	<b>40m</b> (Detail)	210m (Standard)	<b>500m</b> (Standard)



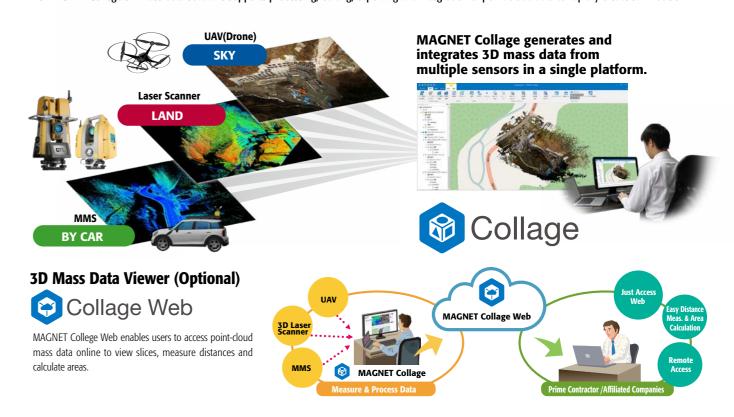






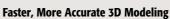
### MAGNET Collage seamlessly connects 3D solution to the site.

The MAGNET College 3D mass-data software supports processing, editing, exporting and integration of point-cloud data to rapidly create 3D models.



### **Allied Office software**





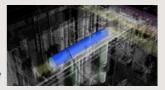


from Point Cloud Data



#### **Construction Verification Software**





#### Floor Flatness and Levelness Analysis Software





### AUTODESK.

The AEC Collection provides designers, engineers, and contractors a set of BIM and CAD tools that support projects from early-stage design through to construction.



- Begin modeling in 3D with accuracy and precision.
- Automatically update floor plans, elevations, and sections as your
- Let Revit handle routine and repetitive tasks with automation so you can focus on higher-value work.



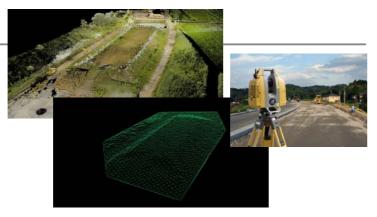
- · Combine design and construction data into a single model.
- Identify and resolve clash and interference problems before construction.
- Aggregate data from multiple trades to better control outcomes.

## **GLS-2200 Applications**

## **GLS-2200**

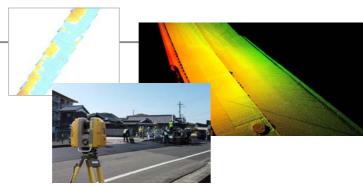
### i-Construction

GLS-2200 meets the needs for i-Construction productivity improvements as promoted by the Japanese Ministry of Land, Infrastructure and Transport (MLIT). Laser scanner and UAV technologies have been leveraged for terrain survey, progress and management of deliverables. This greatly reduces construction time for earthworks, paving, slope shaping and structure-installation works; and simplifies submission of inspection documents.



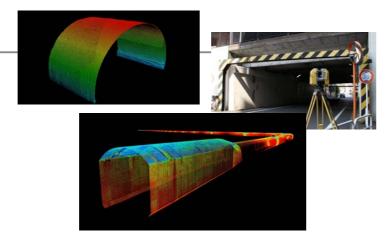
### **Road / slope surface measurement**

Terrestrial Laser Scanner is very effective for road or slope surface measurement. For road surface measurement, the shape of rut on road can be collected and its data can be used for maintenance management purpose. For slope surface measurement, it is effective for measuring disaster areas as well as monitoring deterioration.



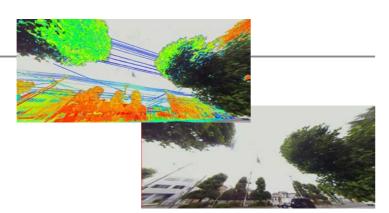
### **Tunnel cross-sections**

create 3D drawings for complex tunnel curves and intersections. Extract cross-sections as needed. Effortlessly compare design data with existing scanned surfaces.



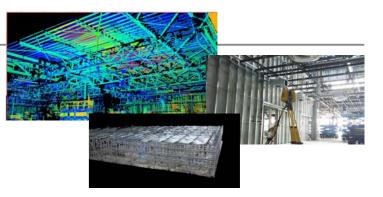
### **Infrastructure inspection**

Measuring the entire structure in 3D allows the scanned data to be used for checking locations that require redesign, and verifying structural sizes and estimating materials.



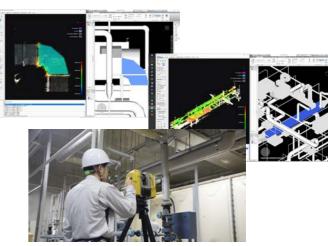
### **BIM** (Building Information Modeling)

The BIM applications include scanning terrains and checking asbuilt renovations of outdoor and indoor areas. You can leverage 3D point cloud data to help with designs, and use the completed scan for future maintenance and renovation.



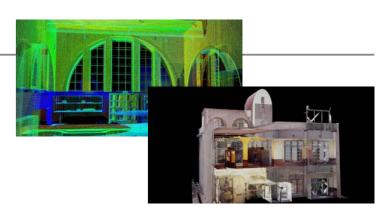
## As-built structural checking facilities

Laser scanning is beneficial for verification of renovations and replacement facilities. Rapid scanning to create accurate point cloud data enables the use of 3D drawings to simulate pipe installations and clash detection.



## Heritage/ and archaeological structures

Laser scanning is invaluable for maintaining and archiving details of historical and archaeological structures that lack any design drawings. The no-contact process enables data to be collected without damaging the structure. Colorized point clouds reproduce the real color of the structure.



#### Reference object to be measured

Range Mode	Reference object to be measured		
Detail	Prominent objects, archaeological sites, historical building, etc.		
High Speed	Accident investigations, disasters areas, short timeframe projects, etc.		
Low Power	Heavy pedestrian areas, laser limitation areas, etc.		
Standard	Large structure, large residential areas, volume measurements, etc.		
Close	Hard-to-measure objects in close proximity with each other.*		
Close (High Power)	Objects which cannot easily be measured, even with CLose mode.		
Road	Existing asphalt or concrete road surface.		
Road (High Power)	New asphalt road surface		
· · · · · · · · · · · · · · · · · · ·			

\* Wet objects, black cables, shiny duct, etc.